

Introduction

➤ Goal:

 Improve the speed of two stream ConvNets for video based action recognition.

Existing works:

- Two-stream ConvNets [1]: Using stacked optical flows and RGB images as inputs to CNN. However, the calculation of optical flows is computationally expensive.
- Efficient feature extraction, encoding and classification for action recognition [3]: Extracting features around motion vector trajectories and using tree-based ANN to accelerate VLAD/Fisher Vector computation.

> Our observations:

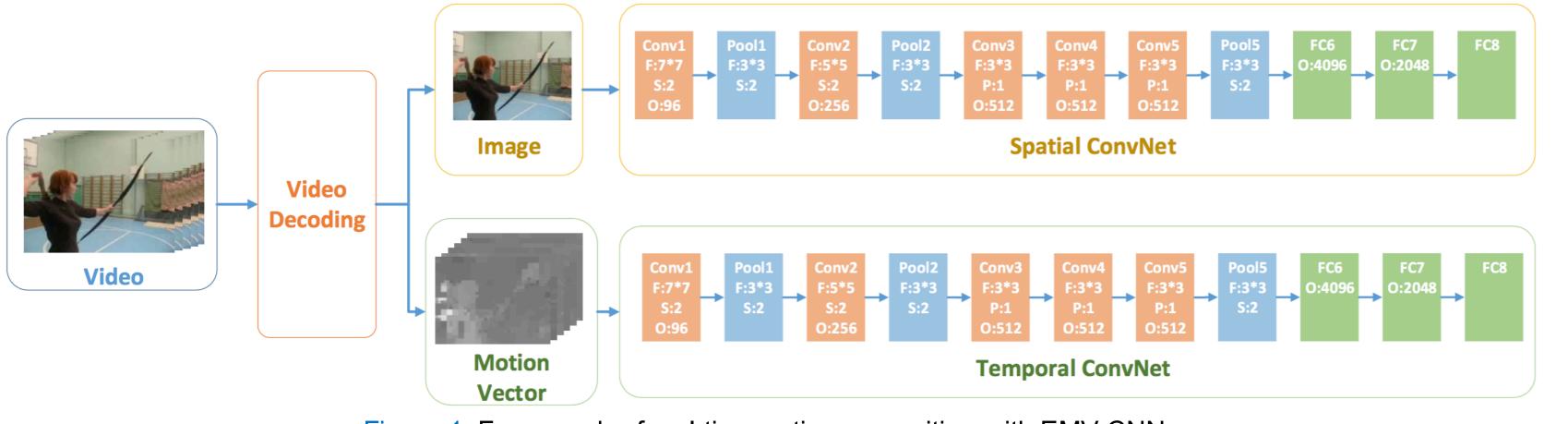
- Calculating optical flow is time consuming while motion vector can be obtained in video decoding process without extra calculation. Please see Table 3 for the speed comparison.
- Optical flow and motion vector share some similar characteristics which allows us to transfer the fine knowledge learned in optical flow CNN (OF-CNN) to motion vector CNN (MV-CNN).

> Our idea: Enhanced Motion Vector CNNs:

- A real-time CNN based action recognition method with high performance is proposed.
- We firstly introduce motion vector as the input of CNN to avoid the heavy computational cost of optical flow.
- We propose techniques to transfer the knowledge of optical flow CNN to motion vector CNN, which significantly improves the recognition performance.

Reference

- K. Simonyan and A. Zisserman. Two-stream convolutional networks for action recognition in videos. In NIPS'14, 2014.
- 2. T. Brox, A. Bruhn, N. Papenberg, and J. Weickert. High accuracy optical flow estimation based on a theory for warping. In ECCV'14, 2004
- V. Kantorov and I. Laptev. Efficient feature extraction, encoding, and classification for action recognition. In CVPR'14, 2014.



> Motion Vector:

Original Frame



Figure 2: Examples of Motion Vector and Optical Flow

Real-time Action Recognition with Enhanced Motion Vector CNNs Bowen Zhang^{1,2} Limin Wang^{1,3} Zhe Wang¹ Yu Qiao^{1*} Hanli Wang²

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Framework of real-time action recognition with EMV-CNN

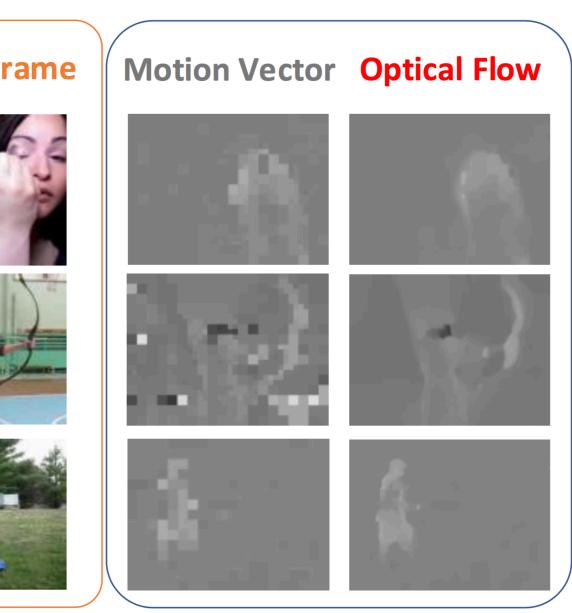
Figure 1: Framework of real-time action recognition with EMV-CNN

Motion Vector

Motion vectors are designed for describing macro blocks movement from one frame to the next, and are widely used in video compression standards.

Motion vectors only contain block-level motion information, which exhibit much coarser structure than optical flows.

As precision motion information is not obligatory for motion vectors, motion vectors contain noisy information.

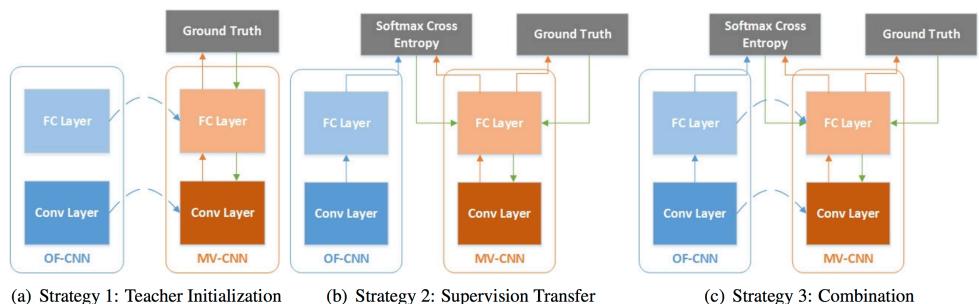


Enhanced Motion Vector CNNs

> Motivation:

- achieve inferior performance.
- MV-CNN.

Enhanced Motion Vector CNNs:



Experiment Results



Using motion vectors can improve the processing speed, but

Due to the coarse structure and inaccurate motion information of motion vectors, it is hard to obtain high performance with

Both optical flows and motion vectors contain motion information. The difference is that optical flows have fine grained structure, while motion vectors contain coarse ones.

In order to enhance MV-CNN, we propose three methods to transfer knowledge from OF-CNN to MV-CNN: Teacher Initialization, Supervision Transfer and their combination.

EMV-CNN vs MV-CNN

Temporal CNN	Accuracy	CNN	MAP
OF-CNN [1]	81.2%	RGB CNN	57.7%
MV-CNN trained from scratch	74.4%	OF-CNN	55.3%
EMV-CNN with ST	77.5%	RGB CNN+OF-CNN	66.1%
EMV-CIVIN with ST EMV-CNN with TI	78.2%	MV-CNN	29.8%
EMV-CININ with TT EMV-CNN with ST+TI	79.3%	EMV-CNN	41.6%
EWVV-CININ WILLISI+II	19.370	RGB CNN+MV-CNN	
Table 1: Performance of different know	ledge	RGB CNN+EMV-CN	N 61.5%

transfer strategies on UCF-101 Split 1

Speed comparison

	Spatial	Brox's Flow [2]	MV
Dataset	Resolution	(GPU) (fps)	(CPU) (fps)
UCF101	320×240	16.7	735.3
THUMOS14	320×180	17.5	781.3

Table 3: Speed of Brox's Flow and MV on UCF101 and THUMOS14

Comparison with state-of-the-art result

Objects (GPU) iDT+CNN (CPU-Motion (iDT+FV) **Objects+Motion** EMV+RGB-CNN

MV+FV (CPU) (re-C3D (1 net) (GPU) C3D (3 net) (GPU) iDT+FV (CPU) Two-stream CNNs EMV+RGB-CNN

 Table 5: Performance on UCF101 (3 splits)

Figure 3: Knowledge transfer strategy from OF-CNN to MV-CNN

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Table 2: Performance on THUMOS-14

	MAP	FPS
	44.7%	_
(+GPU)	62.0%	< 2.38
/) (CPU)	63.1%	2.38
(CPU+GPU)	71.6%	< 2.38
N	61.5%	403.2

Table 4: Performance on THUMOS-14

	Accuracy	FPS
e-implement) [3]	78.5%	132.8
()	82.3%	313.9
()	85.2%	-
	85.9%	2.1
s (GPU)	88.0%	14.3
	86.4%	390.7